

Session		SchCode	Title	Paper#
Interactive Session, INT1 10:45-12:15	Therapeutic Robotics1	WeBINT1.1	Soft Fluidic Actuators of Rotary Type for Safe Physical Human–Machine Interaction Oleg Ivlev* FWBI Research Company & University of Bremen [Germany]	91
		WeBINT1.2	Development of Isokinetic and Iso–Contractile Exercise Machine MEM–MRB” Using MR Brake ” Kunihiro Oda* , Shiro Isono , Yuuki Ohyama , Kazuya Tamida , Takehito Kikuchi , Junji Furusho Osaka Electro–Communication University [Japan]	162
		WeBINT1.3	Time Course of Abnormal Synergies of Stroke Patients Treated and Assessed by a Neuro–Rehabilitation Robot Pin–Cheng Kung , Chou–Ching K Lin* , Ming–Shaung Ju , Shu–Min Chen National Cheng Kung University Hospital [Taiwan]	23
		WeBINT1.4	Error–Enhanced Augmented Proprioceptive Feedback in Stroke Rehabilitation Training: A Pilot Study. Birgit I. Molier* , Jacintha de Boer , G.B. (Gerdienke) Prange , Michiel J.A. Jannink Roessingh Research & Development [Netherlands]	53
		WeBINT1.5	Rehabilitation of Grasping and Forearm Pronation/Supination with the Haptic Knob Olivier Lambercy* , Ludovic Dovat , Hong Yun , Seng Kwee Wee , Christopher Wee Keong Kuah , Karen Sui Geok Chua , Roger Gassert , Theodore Edgar Milner , Chee Leong Teo , Etienne Burdet National University of Singapore [Singapore]	148
		WeBINT1.6	A Randomized Controlled Trial on the Recovery Process of Wrist Rehabilitation Assisted by Electromyography (EMG)–Driven Robot for Chronic Stroke Xiaoling Hu , Kai Yu Tong* , Rong Song , Xiujuan Zheng , W.W.F. Leung The Hong Kong Polytechnic University [China]	85
		WeBINT1.7	Development of Wrist Rehabilitation Equipment Using Pneumatic Parallel Manipulator –Acquisition of P.T.’s Motion and Its Execution for Patient Masahiro Takaiwa* , Toshiro Noritsugu Okayama University [Japan]	100
		WeBINT1.8	Intermanual Transfer of Learning Reveals Representations in Simultaneous Extrinsic and Intrinsic Coordinate Amit Meghani* , Jamie Burgess , James Patton University of Illinois at Chicago [USA]	135
		WeBINT1.9	Analysis of Pick–And–Place, Eating and Drinking Movements for the Workspace Definition of Simple Robotic Che Fai Yeong* , Alejandro Melendez , Etienne Burdet Imperial College London [United Kingdom]	211
		WeBINT1.10	FES Artifact Suppression for Real–Time Tremor Compensation Ferdinan Widjaja* , Cheng Yap Shee , Philippe Poignet , Wei Tech Ang Nanyang Technological University [Singapore]	94
		WeBINT1.11	Upper Limb Rehabilitation of Stroke Participants Using Electrical Stimulation: Changes in Tracking and EMG Ann–Marie Hughes* , Chris T Freeman , Jane Helena Burridge , Paul H Chappell , Paul L Lewin , Eric Rogers University of Southampton [United Kingdom]	89
		WeBINT1.12	Design and Control of an Upper Arm FES Workstation for Rehabilitation Chris T Freeman* , Ann–Marie Hughes , Jane Helena Burridge , Paul H Chappell , Paul L Lewin , Eric Rogers University of Southampton [United Kingdom]	39
Evaluation and Clinical Experience1	WeBINT1.13	A Mobile Gait Monitoring System for Gait Analysis JoonBum Bae* , Kyoungchul Kong , Nancy Byl , Masayoshi Tomizuka University of California, Berkeley [USA]	30	
	WeBINT1.14	Simulation of Clonic Movement with Leg–Robot Driven by Compact MR Fluid Clutch Takehito Kikuchi* , Kunihiro Oda , Junji Furusho Osaka University [Japan]	41	

Interactive Session, INT1 10:45–12:15	WeBINT1.15	Rehabilitation Control Strategies for Gait Robot Via EMG Evaluation and Quantification Ping Wang , K. H. Low* , Hup Boon Lim , Adela Tow Nanyang Technological University [Singapore]	109
	WeBINT1.16	Effects of an Upper Limb Robot–Mediated Therapy on Paretic Upper Limb in Chronic Hemiparetic Subjects: A Biomechanical and EEG–Based Approach for Functional Assessment Stefano Mazzoleni* , Martina Coscia , Giulia Rossi , Sara Aliboni , Federico Posteraro , Maria Chiara Carrozza Scuola Superiore Sant'Anna [Italy]	81
	WeBINT1.17	T–TOAT: A Method of Task–Oriented Arm Training for Stroke Patients Suitable for Implementation of Exercises in Rehabilitation Technology Annick. A. A. Timmermans* , Richard P. J. Geers , Johan A. Franck , Paul Dobbeltijn , Annemie I.F. Spooren , Herman Kingma , Henk A.M. Seelen Rehabilitation Foundation Limburg (SRL) [Netherlands]	104
	WeBINT1.18	Acceptability of Robot Assisted Active Arm Exercise As Part of Rehabilitation after Stroke Andrew Edward Jackson* , Sophie Makower , Peter Robert Culmer , Ray Holt , Alastair Cozens , Martin Levesley , Bipin Bhakta University of Leeds [United Kingdom]	117
Robotics for Human–Motion Analysis1	WeBINT1.19	Realtime Identification Software for Human Whole–Body Segment Parameters Using Motion Capture and Its Visualization Interface Gentiane Venture* , Ko Ayusawa , Yoshihiko Nakamura Tokyo University of Agriculture and Technology [Japan]	31
	WeBINT1.20	Waseda Bioinstrumentation System #3 As a Tool for Objective Rehabilitation Measurement and Assessment – Development of the Inertial Measurement Unit – Salvatore Sessa* , Massimiliano Zecca , Zhuohua Lin , Tomoya Sasaki , Kazuko Itoh , Atsuo Takanishi Waseda University [Japan]	187
	WeBINT1.21	Development of Mechanical Load Adjusting Device with Motion Measurement Interface for Robotic Assistive Rehabilitation System Toru Tsumugiwa* , Yuki Watanabe , Ryuichi Yokogawa Doshisha University [Japan]	102
	WeBINT1.22	MIMICS: Multimodal Immersive Motion Rehabilitation of Upper and Lower Extremities by Exploiting Biocooperation Principles Marko Munih* , Robert Riener , Gery Colombo , Volker Dietz , Lars Lunenburger , Friedemann Mueller , Mel Slater , Matjaž Mihelj University of Ljubljana [Slovenia]	120
	WeBINT1.23	Motor Task Planning for Neuromuscular Function Tests Using an Individual Muscle Control Technique Jun Ueda* , Moiz Hyderabadwala Georgia Institute of Technology [USA]	146
	WeBINT1.24	An Automated Metrics Set for Mutual Adaptation between Human and Robotic Device Dana Damian* , Alejandro Hernandez Arieta , Max Lungarella , Rolf Pfeifer University of Zurich [Switzerland]	37
	WeBINT1.25	Stochastic Estimation of Human Arm Impedance under Nonlinear Friction in Robot Joints: A Model Study Pyung Hun Chang , Sang Hoon Kang* KAIST [Korea, South]	98
	WeBINT1.26	Visuo–Manual Tracking in a Robot–Generated Dynamic Environment Valentina Squeri* , Lorenzo Masia , Elena Vergaro , Maura Casadio , Pietro Giovanni Morasso , Vittorio Università di Genova [Italy]	126

Interactive Session, INT1 10:45–12:15	Artificial Human Exoskeletons 1	WeBINT1.27	Design of a Single-Dof Active Hand Orthosis for Neurorehabilitation Giulio Rosati*, Stefano Cenci, Giovanni Boschetti, Damiano Zanotto, Stefano Masiero University of Padua [Italy]	111
		WeBINT1.28	Design of a Flexible Fluidic Actuation System for a Hybrid Elbow Orthosis Christian Pylatiuk*, Artem Kargov, Immanuel Gaiser, Tino Werner, Stefan Schulz, Georg Bretthauer Forschungszentrum karlsruhe gmbh [Germany]	124
		WeBINT1.29	Orthopaedic Rehabilitation – a Powered Elbow Orthosis Using Compliant Actuation Innes Vanderniepen*, Ronald Van Ham, Dirk Lefever Vrije Universiteit Brussel [Belgium]	198
		WeBINT1.30	Mechanical Designs of Active Upper-Limb Exoskeleton Robots State-Of-The-Art and Design Difficulties Ranathunga Arachchilage Ruwan Chandra Gopura, Kazuo Kiguchi* Saga University [Japan]	20
		WeBINT1.31	Development of a New Exoskeleton for Upper Limb Rehabilitation Rocco Vertechy*, Antonio Frisoli, Andrea Dettori, Massimiliano Solazzi, Massimo Bergamasco Scuola Superiore Sant' Anna [Italy]	173
		WeBINT1.32	Finger Exoskeleton for Treatment of Tendon Injuries Hakan Ertas, Elif Hocaoglu, Duygun Erol Barkana, Volkan Patoglu* Sabanci University [Turkey]	191
		WeBINT1.33	Design of Redundant Drive Joint with Adjustable Stiffness and Damping to Improve Joint Admittance Kiyoshi Nagai, Yosuke Ikegami*, Rui C. V. Loureiro, William Harwin Ritsumeikan University [Japan]	214
Interactive Session, INT2 15:15–16:45	Cybernetics	WeDINT2.1	Standing-Up Motion Support for Paraplegic Patient with Robot Suit HAL Atsushi Tsukahara*, Yasuhisa Hasegawa, Yoshiyuki Sankai University of Tsukuba [Japan]	95
		WeDINT2.2	Gait Rehabilitation for Stair Climbing with a Locomotion Interface Hiroaki Yano*, Shintarou Tamefusa, Naoki Tanaka, Hideyuki Saitou, Hiroo Iwata University of Tsukuba [Japan]	206
		WeDINT2.3	Fingertip Stiffness Control Using Polyarticular Tendon Drive System Masahiro Iwaki*, Yasuhisa Hasegawa, Yoshiyuki Sankai University of Tsukuba [Japan]	205
		WeDINT2.4	Analysis of Surface EMG Signal Based on Empirical Mode Decomposition Min Lei* Shanghai Jiao Tong University [China]	60
		WeDINT2.5	Position Control of SMA Actuator for 3D Tactile Display Teeranoot Chanthalasopeephan* King Mongkut's University of Technology Thonburi [Thailand]	110
		WeDINT2.6	Multichannel Audio Aided Dynamical Perception for Prosthetic Hand Biofeedback Jose Eduardo Gonzalez Vargas*, Wenwei Yu Chiba University [Japan]	149
	Artificial Human Exoskeletons 2	WeDINT2.7	Design of a Joint-Coupled Orthosis for FES-Aided Gait Ryan Farris*, Hugo Quintero, Thomas Withrow, Michael Goldfarb Vanderbilt University [USA]	28
		WeDINT2.8	Gait Trials of an Active AFO for Achilles Tendon Ruptures Nobuyuki Yoshizawa* Nippon Institute of Technology [Japan]	34

Interactive Session, INT2 15:15–16:45	WeDINT2.9	Design of a Reconfigurable Ankle Rehabilitation Robot and Its Use for the Estimation of Ankle Impedance Aykut Cihan Satici , Ahmetcan Erdogan , Volkan Patoglu* Sabanci University [Turkey]	156
	WeDINT2.10	Gait and Neuromuscular Learning Effects through the Use of a Gait Monitoring System Jody L. Riskowski* University of Texas at El Paso [USA]	65
	WeDINT2.11	Gait Planning for Effective Rehabilitation – from Gait Study to Application in Clinical Rehabilitation K. H. Low* Nanyang Technological University [Singapore]	57
	WeDINT2.12	Safe and Compliant Guidance in Robot-Assisted Gait Rehabilitation Using Proxy-Based Sliding Mode Control Pieter Beyl* , Micha Van Damme , Pierre Cherelle , Dirk Lefeber Vrije Universiteit Brussel [Belgium]	165
	WeDINT2.13	Monitoring Method of Interactive Torque between Human and Robot in Exoskeleton Systems Beomsoo Hwang , Hyosang Moon* Sogang university [Korea, South]	210
Neural-Machine Interfaces & Control	WeDINT2.14	Estimation of Finger Joint Angles from Semg Using a Recurrent Neural Network with Time-Delayed Input Masaaki Hioki* , Haruhisa Kawasaki Gifu University [Japan]	43
	WeDINT2.15	Human Forearm Motion Discrimination Based on Myoelectric Signal by Fuzzy Inference Atsushi Kiso* , Hirokazu Seki Chiba Institute of Technology [Japan]	72
	WeDINT2.16	Comparison of Surface EMG Monitoring Electrodes for Long-Term Use in Rehabilitation Device Control Christian Pylatiuk* , Meinolf Mller-Riederer , Artem Kargov , Stefan Schulz , Georg Breithauer Forschungszentrum Karlsruhe gmbh [Germany]	87
	WeDINT2.17	Thumb-Tip Force Estimation from Semg and a Musculoskeletal Model for Real-Time Finger Prosthesis Wonil Park , Suncheol Kwon , Hae-Dong Lee , Jung Kim* KAIST [Korea, South]	152
	WeDINT2.18	A Study on Classification of Upper Limb Motions from Around-Shoulder Muscle Activities Yuse Horiuchi* , Wenwei Yu Chiba Univ [Japan]	209
	WeDINT2.19	Fundamental Research about Electroencephalogram (EEG) – Functional Electrical Stimulation (FES) Rehabilitation System Mitsuru Takahashi* , Manabu Gouko , Koji Ito Tokyo Institute of Technology [Japan]	84
	WeDINT2.20	Evaluation of the Bremen SSVEP Based BCI in Real World Conditions Ivan Volosyak* , Hubert Cecotti , Diana Valbuena , Axel Gräer University of Bremen [Germany]	123
	WeDINT2.21	Wearable Stimulator for SSVEP-Based Brain-Computer Interfaces Thorsten Lüth* , Axel Gräer University of Bremen [Germany]	113
	WeDINT2.22	Motor Imagery in Robot-Assistive Rehabilitation: A Study with Healthy Subjects Muhammad Nabeel Anwar* , Vittorio Sanguineti , Pietro Giovanni Morasso , Koji Ito Tokyo Institute of Technology [Japan]	119
	WeDINT2.23	Environment Discrimination with Vibration Feedback to the Foot, Arm, and Fingertip Netta Gurari* , Kathryn Smith , Manu Madhav , Allison M. Okamura Johns Hopkins University [USA]	164

Interactive Session, INT2 15:15–16:45	Therapeutic Robotics2	WeDINT2.24	Novel Home-Based Rehabilitation Device to Prevent Secondary Diseases for Patients with Spinal Cord Injury Noritaka Kawashima*, Rie Suzuki , Kimitaka Nakazawa , Yuji Ohta Research Inst., National Rehabilitation Center for Persons with Disability [Japan]	118
		WeDINT2.25	Real-Time Fuzzy Trajectory Generation for Robotic Rehabilitation Therapy Peter Martin , M. Reza Emami* University of Toronto [Canada]	136
		WeDINT2.26	Discussion of Sling Control Simulation in Feedback Type Gait Training System Hidetaka Ikeuchi*, Shingo Takiyama , Yukio Saito Oita University [Japan]	93
		WeDINT2.27	Adaptive Control of an Endeffector Based Electromechanical Gait Rehabilitation Device Sami Hussein* , Henning Schmidt , Jörg Krüger TU Berlin [Germany]	195
		WeDINT2.28	Interaction Control of a Programmable Footpad-Type Gait Rehabilitation Robot for Active Walking on Various Bondhan Novandy* , Jungwon Yoon Gyeongsang National University [Korea, South]	122
		WeDINT2.29	Effects of a Robot-Mediated Locomotor Training on EMG Activation in Healthy and SCI Subjects Stefano Mazzoleni* , Giulia Stampacchia , Emanuele Cattin , Eleonora Bradaschia , Martina Tolaini , Bruno Rossi , Maria Chiara Carrozza Scuola Superiore Sant'Anna [Italy]	79
		WeDINT2.30	A New Robotic Platform for Gait Rehabilitation of Bedridden Stroke Patients Vito Monaco* , Giuseppe Galardi , Je Hyung Jung , Sergio Bagnato , Cristina Boccagni , Silvestro Micera ARTS Lab, Scuola Superiore Sant'Anna [Italy]	115
		WeDINT2.31	Influence on Walking Dynamics of a Gait Training Device That Is Connected through a Lumbar Belt Jan Veneman* , Dejan Popovic , Thierry Keller Fatronik-Tecnalia [Spain]	108
		WeDINT2.32	MotionTherapy@Home • a Robotic Device for Automated Locomotion Therapy at Home Ruediger Rupp* , Harry Plewa , Eberhard Hofer , Markus Knestel Orthopedic University Hospital [Germany]	176
		WeDINT2.33	Increases in Overground Gait Speed with Body Weight Support in People Post-Stroke Jamie Burgess*, Gwendolyn Weibel, David Brown Northwestern University [USA]	137
Interactive Session, INT3 10:45–12:15	Bio-cooperative Robotics	ThBINT3.1	Bio-Cooperative Robotics: Controlling Mechanical, Physiological and Mental Patient States Robert Riener* , Alexander Christian Koenig , Bolliger Marc , Martin Wieser , Alexander Duschau-Wicke , Heike ETH Zurich [Switzerland]	36
		ThBINT3.2	Adaptive Body Weight Support Controls Human Activity During Robot-Aided Gait Training Alexander Duschau-Wicke* , Simon Felsenstein , Robert Riener ETH Zurich [Switzerland]	32
		ThBINT3.3	Voluntary Gait Speed Adaptation for Robot-Assisted Treadmill Training Alexander Christian Koenig* , Carmen Binder , Joachim v. Zitzewitz , Ximena Omlin , Bolliger Marc , Robert ETH Zurich [Switzerland]	68
		ThBINT3.4	Biocooperation in Rehabilitation Robotics of Upper Extremities Marko Munih* , Domen Novak , Tadej Bajd , Matjaž Mihelj University of Ljubljana [Slovenia]	52

Interactive Session, INT3 10:45–12:15		ThBINT3.5	Haptic Training of Lower Extremities Enhanced by Visual Modality Tomaz Koritnik*, Alexander Christian Koenig, Tadej Bajd, Robert Riener, Marko Munih University of Ljubljana [Slovenia]	35
		ThBINT3.6	A Universal Haptic Device for Arm and Wrist Rehabilitation Jakob Oblak*, Imre Cikajlo, Zlatko Matjačić Institute for rehabilitation [Slovenia]	50
Mental and Physical Rehabilitation Engineering		ThBINT3.7	Methodological Consideration for the Recruitment of Upper Limb Muscles During Two Joint Arm Movements Tasuku Miyoshi*, Yoshiyuki Takahashi, Lee Hokyoo, Masaki Yamaguchi, Takashi Komeda Iwate University [Japan]	21
		ThBINT3.8	Mental Health Evaluation Using Chemical Sensor As Human–Machine Interface Yusuke Tahara*, Takayuki Takahashi, Kazunori Takeda, Tasuku Miyoshi, Masaki Yamaguchi Iwate University [Japan]	66
		ThBINT3.9	A Study on Power-Assisted Rehabilitation Robot Arms Operated by Patient with Upper Limb Disabilities Atushi Umemura*, Yukio Saito Tokyo Denki University [Japan]	160
		ThBINT3.10	Development of Oral Rehabilitation Robot WAO-1R Designed to Provide Various Massage Techniques Jorge Solis*, Yuichi Obokawa, Hiroyuki Ishii, Hiroki Koga, Atsuo Takanishi, Akitoshi Katsumata Waseda University [Japan]	103
		ThBINT3.11	Integration of Error Augmentation Training Method to an Assistive Controller for Rehabilitation Robotic Furui Wang*, Duygun Erol Barkana, Nilanjan Sarkar Vanderbilt University [USA]	76
		ThBINT3.12	Patient–Tracking for an Over-Ground Gait Training System Tobias Nef*, David Brennan, Iian Black, Joe Hidler The Catholic University of America [USA]	138
		ThBINT3.13	Negative Viscosity Can Enhance Learning of Inertial Dynamics. Felix Huang*, James Patton, Ferdinando Mussa-Ivaldi Rehabilitation Institute of Chicago [USA]	139
		ThBINT3.14	Development of an Isokinetic FES Leg Stepping Trainer (iFES–LST) for Individuals with Neurological Disability Nur Azah Hamazaid*, Che Fornusek, Andrew Ruys, Glen Davis The University of Sydney [Australia]	96
Assistive Robotics1		ThBINT3.15	Estimation of Intention of User Arm Motion for the Proactive Motion of Upper Extremity Supporting Robot Taisuke Sakaki* [Japan] Kyushu Sangyo University	40
		ThBINT3.16	Development of a Human Symbiotic Assist Arm PAS-Arm Mineo Higuchi*, Tsukasa Ogasawara Mitsubishi Electric Corporation [Japan]	58
		ThBINT3.17	Tremor Suppression Control of Meal–Assist Robot with Adaptive Filter Eiichi Ohara, Ken’ichi Yano*, Satoshi Horihata, Takaaki Aoki, Yutaka Nishimoto Gifu University [Japan]	97
		ThBINT3.18	An Empirical Study with Simulated ADL Tasks Using a Vision–Guided Assistive Robot Arm Dae-Jin Kim*, Ryan Lovelett, Aman Behal University of Central Florida [USA]	143
	ThBINT3.19	A List of Household Objects for Robotic Retrieval Prioritized by People with ALS Young Sang Choi*, Travis Deyle, Tiffany Chen, Jonathan Glass, Charlie Kemp Georgia Institute of Technology [USA]	199	

Interactive Session, INT3 10:45–12:15		ThBINT3.20	Design, Simulation and Testing of a New Modular Wheelchair Mounted Robotic Arm to Perform Activities of Peter Schrock , Fabian Farelo , Redwan Alqasemi* , Rajiv Dubey University of South Florida [USA]	217
		ThBINT3.21	A Universal Mobile Robot for Assistive Tasks Motoki Takagi* , Yoshiyuki Takahashi , Takashi Komeda Shibaura Institute of Technology [Japan]	56
		ThBINT3.22	Robotic Assistance with Attitude: A Mobility Agent for Motor Function Rehabilitation and Ambulation Support Jaime Valls Miro* , Vivien Osswald , Mitesh Patel , Gamini Dissanayake University of Technology Sydney [Australia]	147
		ThBINT3.23	Generalized Elasticities Improve Patient–Cooperative Control of Rehabilitation Robots Heike Vallery* , Alexander Duschau-Wicke , Robert Riener ETH Zurich [Switzerland]	64
Therapeutic Robotics3		ThBINT3.24	MIT–Skywalker Caitlyn Joyce Bosecker , Hermano Igo Krebs* MIT [USA]	69
		ThBINT3.25	Design of a New Lower Extremity Orthosis for Overground Gait Training with the WalkTrainer Yves Allemand* , Yves Stauffer , Reymond Clavel , Roland Brodard Fondation Suisse pour les Cyberthèses (FSC) [Switzerland]	75
		ThBINT3.26	Control System for Lower Limb Function Training Device by Using Internal Model Control Ryoichi Suzuki* , Nobuaki Kobayashi , Eberhard Hofer Kanazawa Institute of Technology [Japan]	128
		ThBINT3.27	Design and Control of Two Planar Cable–Driven Robots for Upper–Limb Neurorehabilitation Giulio Rosati* , Damiano Zanotto , Riccardo Secoli , Aldo Rossi University of Padua [Italy]	114
		ThBINT3.28	Development of Evaluation System of the Motor Function for Upper Limbs Using 3–D Rehabilitation Robot “EMUL” and Near-Infrared Spectroscopy “NIRS” Makoto Haraguchi* , Takehito Kikuchi , Masahito Miura , Megumi Hatakenaka , Ichiro Miyai , Junji Furusho Osaka University [Japan]	153
		ThBINT3.29	Modular Robotics for Playful Physiotherapy Henrik Hautop Lund* Technical University of Denmark [Denmark]	150
Evaluation and Clinical Experience2		ThBINT3.30	Arm Training in Multiple Sclerosis Using Phantom: Clinical Relevance of Robotic Outcome Measures Peter Feys* , Geert Alders , Domien Gijbels , Karin Coninx , Chris Raymaekers , Joan De Boeck , Tom Deweyer , Veronik Truyens , Patric Groenen , Hans Savelberg , Kenneth Meijer , Bert Eijnde O University College (PHL) and University of Hasselt [Belgium]	47
		ThBINT3.31	A User–Centered Evaluation Study of a Mobile Arm Support Katarina Lund , Richard Brandt , Gert Jan Gelderblom , Just Herder* Delft University of Technology [Netherlands]	186
		ThBINT3.32	Tracking and Analysis of Human Head Motion During Guided Fmri Motor Tasks Ningbo Yu* , Robert Riener ETH Zurich [Switzerland]	38
		ThBINT3.33	Intuitiveness Facilitates Rehabilitation: Clinical Results Ludovic Saint–Bauzel* , Viviane Pasqui , Isabelle Monteil Université Pierre et Marie Curie–Paris6 [France]	121
		ThBINT3.34	Selective and Adaptive Robotic Support of Foot Clearance for Training Stroke Survivors with Stiff Knee Gait Edwin van Asseldonk* , Bram Koopman , Jaap Buurke , Corien Simons , Herman Van der Kooij University of Twente [Netherlands]	158

Interactive Session, INT4 16:00-17:30	Robotics for Caregiving	ThDINT4.1	Development of Multi-Functional Robotic Test-Bed for Post-Surgical Healthcare Room Feng-Li Lian* National Taiwan University [Taiwan]	16
		ThDINT4.2	Unrestraint Support Robot for Elderly Gait Rehabilitation Makoto Nokata* , Wataru Hirai Ritsumeikan University [Japan]	105
		ThDINT4.3	A Proposal of a Method to Reduce Burden of Excretion Care Using Robot Technology Keiko Homma* , Yoji Yamada , Osamu Matsumoto , Eiichi Ono , Suwoong Lee , Mikio Horimoto , Takahiro Suzuki , Noriyuki Kanehira , Toshiaki Suzuki , Shinichiro Shiozawa National Institute of Advanced Industrial Science and Technology (AIST) [Japan]	144
		ThDINT4.4	Self-Aided Manipulator System for Bed-Ridden Patients – Evaluation of Psychological Influence for the Generated Approach Motion – Akihiko Hanafusa* , Johta Sasaki , Teruhiko Fuwa , Tomozumi Ikeda Shibaura Institute of Technology [Japan]	159
		ThDINT4.5	A First Step towards a Pervasive and Smart ZigBee Sensor System for Assistance and Rehabilitation Filippo Cavallo* , Michela Aquilano , Luca Odetti , Maria Chiara Carrozza Scuola Superiore Sant'Anna – Pisa [Italy]	215
		ThDINT4.6	Self-Contained Powered Knee and Ankle Prosthesis: Initial Evaluation on a Transfemoral Amputee Frank Sup* , Huseyin Atakan Varol , Jason Mitchell , Thomas Withrow , Michael Goldfarb Vanderbilt University [USA]	24
		ThDINT4.7	Powered Sit-To-Stand and Assistive Stand-To-Sit Framework for a Powered Transfemoral Prosthesis Huseyin Atakan Varol* , Frank Sup , Michael Goldfarb Vanderbilt University [USA]	80
		ThDINT4.8	Successful Walking with a Biologically-Inspired Below-Knee Prosthesis Rino Versluys* , Ronald Van Ham , Innes Vanderniepen , Dirk Lefeber Vrije Universiteit Brussel [Belgium]	133
		ThDINT4.9	Powered Ankle-Foot System That Mimics Intact Human Ankle Behavior: Proposal of a New Concept Rino Versluys* , Arnout Matthys , Ronald Van Ham , Innes Vanderniepen , Dirk Lefeber Vrije Universiteit Brussel [Belgium]	134
		ThDINT4.10	Precise Position and Trajectory Control of Pneumatic Soft-Actuators for Assistance Robots and Motion Therapy Devices Mathias Jordan , Dennis Pietrusky , Miroslav Mihajlov , Oleg Ivlev* FWBI Research Company & University of Bremen [Germany]	92
		ThDINT4.11	Feasibility Study of a New Powered Humeral Rotator for Upper Limb Myoelectric Prostheses Raffaele Caminati , Marco Troncossi* , Angelo Davalli , Vincenzo Parenti Castelli University of Bologna [Italy]	170
		ThDINT4.12	Design of a Multifunctional Anthropomorphic Prosthetic Hand with Extrinsic Actuation Skyler Dalley* , Tuomas Wiste , Thomas Withrow , Michael Goldfarb Vanderbilt University [USA]	181
		ThDINT4.13	Progress Towards the Development of the SmartHand Transradial Prosthesis Christian Cipriani* , Marco Controzzi , Maria Chiara Carrozza Scuola Superiore Sant'Anna [Italy]	33

Interactive Session, INT4 16:00-17:30	Robotics for Human–Motion Analysis2	ThDINT4.15	Tracking Target Motion under Combined Visual and Kinesthetic Disturbance Lorenzo Masia* , Valentina Squeri , Maura Casadio , Pietro Giovanni Morasso , Vittorio Sanguineti , Giulio Italian Institute of Technology [Italy]	125
		ThDINT4.16	The Development of an Assistive Robot for Improving the Joint Attention of Autistic Children Ravindra Senarathna De Silva* , Katsunori Tadano , Azusa Saito , Stephen G. Lambacher , Masatake Higashi Toyota Technological Institute [Japan]	77
		ThDINT4.17	Dynamical Role Division between Two Subjects in a Crank–Rotation Task Ryohei Ueha* , Hang Pham , Hiroaki Hirai , Fumio Miyazaki Osaka University [Japan]	78
		ThDINT4.18	An Artificial Reflex Improves the Perturbation–Resistance of Normal and Spastic Walking – a Simulation Study Yu Ikemoto* , Wenwei Yu , Jun Inoue Chiba University [Japan]	112
		ThDINT4.19	Adaptation to Knee Flexion Torque During Gait James Sulzer* , Keith Edward Gordon , T. George Hornby , Michael Peshkin , James Patton Northwestern University/Rehabilitation Institute of Chicago [USA]	174
		ThDINT4.20	Torque Estimation System for Human Leg in Passive Motion Using Parallel–Wire Driven Mechanism and Iterative Learning Control Hitoshi Kino* , Kenichi Saisyo , Yasuhiko Hatanaka , Sadao Kawamura Fukuoka Institute of Technology [Japan]	55
Assistive Robotics2		ThDINT4.21	Fuzzy Logic Based Regenerative Braking Control System of Electric Wheelchair for Senior Citizen Yoshiaki Takahashi* , Hirokazu Seki Chiba Institute of Technology [Japan]	70
		ThDINT4.22	Adaptive Collaborative Assistance for Wheelchair Driving Via CBR Learning Cristina Urdiales* , Jose Manuel Peula Palacios , Manuel Fernandez–Carmona , Roberta Annicchiarico , Francisco Sandoval , Carlo Caltagirone Universidad de Málaga [Spain]	86
		ThDINT4.23	Efficiency Based Collaborative Control Modulated by Biometrics for Wheelchair Assisted Navigation Manuel Fernandez–Carmona* , Blanca Fernández–Espejo , Jose Manuel Peula Palacios , Cristina Urdiales , Francisco Sandoval Universidad de Málaga [Spain]	88
		ThDINT4.24	Controlling an Automated Wheelchair Via Joystick/Head–Joystick Supported by Smart Driving Assistance Thomas Röfer* , Christian Mandel , Tim Laue Deutsches Forschungszentrum für Künstliche Intelligenz [Germany]	168
		ThDINT4.25	Detection Mechanism of Manipulation Torque for One Hand Drive Wheelchair with a Triple Ring Kazuaki Sakai* , Toshihiko Yasuda , Katsuyuki Tanaka Northeastern Industrial Research Center [Japan]	212
Therapeutic Robotics4		ThDINT4.26	Reach & Grasp Therapy: Effects of the Gentle/G System Assessing Sub–Acute Stroke Whole–Arm Rehabilitation Rui C. V. Loureiro* , Bob Lamperd , Christine Collin , William Harwin The University of Reading [United Kingdom]	161
		ThDINT4.27	Developing a whole-arm exoskeleton robot with Hand Opening and Closing Mechanism for Upper Limb Stroke Rehabilitation Yupeng Ren , Hyung–Soon Park , Li–Qun Zhang* Rehabilitation Institute of Chicago/Northwestern University [USA]	204

Interactive Session, INT4 16:00-17:30		ThDINT4.28	Enhancing Exploratory Learning Behaviour in People with Stroke Undertaking Ipam Robot Assisted Upper Limb Peter Robert Culmer*, Andrew Edward Jackson, Sophie Makower, Robert Richardson, Alastair Cozens, Martin Levesley, Bipin Bhakta University of Leeds [United Kingdom]	106
		ThDINT4.29	Assessment and Training of Synergies with an Arm Rehabilitation Robot Marco Guidali*, Mark Schmiedeskamp, Verena Klamroth, Robert Riener ETH Zurich [Switzerland]	155
		ThDINT4.30	Interactive Rehabilitation Robot for Hand Function Training Mo Chen, S.K. Ho, H.F. Zhou, P.M.K. Pang, Xiaoling Hu, David T.W. Chan, Kai Yu Tong* The Hong Kong Polytechnic University [China]	101
		ThDINT4.31	Hybrid-PLEMO™, Rehabilitation System for Upper Limbs with Active / Passive Force Feedback, and Its Application for Facilitation Techniques Takehito Kikuchi*, Takuya Ozawa, Hiroki Akai, Junji Furusho Osaka University [Japan]	67
		ThDINT4.32	Development of Rehabilitation Support Robot for Personalized Rehabilitation of Upper Limbs Yuichi Furuhashi*, Yoshifumi Morita Nagoya Institute of Technology [Japan]	145
Interactive Session, INT5 11:00-12:30	Robotics for Human–Motion Analysis3	FrBINT5.1	Impact of Visual Error Augmentation Methods on Task Performance and Motor Adaptation Ozkan Celik*, Dane Powell, Marcia O’Malley Rice University [USA]	17
		FrBINT5.2	Validation of a Smooth Movement Model for a Human Reaching Task Joel C. Huegel*, Andrew Lynch, Marcia O’Malley Rice University [USA]	15
		FrBINT5.3	Shoulder, Elbow and Wrist Stiffness in Passive Movement and Their Independent Control in Voluntary Movement Post Stroke Li–Qun Zhang*, Hyung–Soon Park, Yupeng Ren Rehabilitation Institute of Chicago/Northwestern University [USA]	189
		FrBINT5.4	Characterization of Multi-Finger Twist Motion Toward Robotic Rehabilitation Reinhold Scherer*, Sujata Pradhan, Daniel Kim, Brian Dellon, Roberta Klatzky, Yoky Matsuoka University of Washington [USA]	216
		FrBINT5.5	An Approach to Sensor Fusion in Medical Robots John Avor*, Thompson Sarkodie–Gyan University of Texas at El Paso [USA]	188
		FrBINT5.6	Gait Variability While Walking with Three Different Speeds Huiying Yu*, Jody L. Riskowski, Thompson Sarkodie–Gyan University of Texas at El Paso [USA]	196
		FrBINT5.7	Optimization of Diagnosis and Therapy in Human Gait Thompson Sarkodie–Gyan* University of Texas at El Paso [USA]	190
	Evaluation and Clinical Experience3	FrBINT5.8	Rehabilitation Robotics in Robotics for Healthcare; a Roadmap Study for the European Commission Gert Jan Gelderblom*, Monique de Wilt, Ger Cremers, Arjan Rensma Vilans [Netherlands]	179

Interactive Session, INT5 11:00-12:30	FrBINT5.9	Walking Speed and Slope Estimation Using Shank-Mounted Inertial Measurement Units Qingguo li* , Mei Young , Veronica Naing , Max Donelan Queen's University [Canada]	63
	FrBINT5.10	Effect of Different Training Modes on Ground Reaction Forces During Robot Assisted Floor Walking and Stair Sami Hussein* , Henning Schmidt , Stefan Hesse , Jörg Krüger TU Berlin [Germany]	194
	FrBINT5.11	Walking Analysis of a Dual-Track Treadmill Using a Foot-Platform Locomotion Interface Jungwon Yoon* , Jeha Ryu Gyeongsang National University [Korea, South]	213
	FrBINT5.12	Intelligently Controllable Ankle Foot Orthosis (I-AFO) and Its Application for a Patient of Guillain-Barre Sosuke Tanida* , Takehito Kikuchi , Taigo Kakehashi , Kikuko Otsuki , Takuya Ozawa , Takamitsu Fujikawa , Takashi Yasuda , Junji Furusho , Shoji Morimoto , Yasunori Hashimoto Osaka University [Japan]	71
	FrBINT5.13	Clinical Evaluation of a Low--Cost Alternative for Stroke Rehabilitation Luis Enrique Sucar* , Ronald Leder Instituto Nacional de Astraafisica, Optica y Electraonica [Mexico]	141
	FrBINT5.14	An Explorative Study into Changes in Reach Performance after Gravity Compensation Training in Chronic Stroke Patients G.B. (Gerdienke) Prange* , Thijs Krabben , G.J. Renzenbrink , Jacintha de Boer , Hermie J Hermens , Michiel J.A. Jannink Roessingh Research & Development [Netherlands]	129
	FrBINT5.15	Initial Clinical Tests for Assessment Models of Synergy Movements of Stroke Patients Using PLEMO System with Sensor Grip Device Takuya Ozawa* , Takehito Kikuchi , Kazuki Fukushima , Fukuda Takahiro , Sosuke Tanida , Takamitsu Fujikawa , Shigeaki Kano , Hirokiakai , Junji Furusho Osaka University [Japan]	74
	FrBINT5.16	Developing a User Interface for the iPAM Stroke Rehabilitation System Stephanie Kemna* , Peter Robert Culmer , Andrew Edward Jackson , Sophie Makower , Justin Francis Gallagher , Ray Holt , Fokie Cnossen , Alastair Cozens , Martin Levesley , Bipin Bhakta University of Groningen [Netherlands]	163
	FrBINT5.17	Relation between Ability to Track Force During Dual Tasking and Function in Individuals with Parkinson's Sujata Pradhan* , Bambi Brewer , George Carvell , Patrick Sparto , Anthony Delitto , Yoky Matsuoka University of Washington [USA]	140
	FrBINT5.18	Audio Image Rendering for the Severely Visually Impaired Sepideh Hajipour , Niloufar Babapour Khosravi , Edmond Zahedi* Sharif University of Technology [Iran]	29
the Use of Robots in Play for Children with Disabilities	FrBINT5.19	Modular Playware as a Playful Diagnosis Tool for Autistic Children Henrik Hautop Lund* Technical University of Denmark [Denmark]	51
	FrBINT5.20	Supporting Narrative Understanding of Children with Autism: A Story Interface with Autonomous Autobiographic Agents Wan Ching Ho* , Megan Davis , Kerstin Dautenhahn University of Hertfordshire [United Kingdom]	82
	FrBINT5.21	A Unified, Neuro-Physio Platform to Facilitate Collaborative Play in Children with Learning Disabilities Subhasis Banerji , Kok Hui, John Heng* Nanyang Technological University [Singapore]	127

Interactive Session, INT5 11:00-12:30		FrBINT5.22	A Robotic Toy for Children with Special Needs: From Requirements to Design Patrizia Marti , Leonardo Giusti , Claudio Moderini , Alessandro Pollini* University of Siena [Italy]	175
	Companion Robots in Eldercare	FrBINT5.23	The Use of Socially Assistive Robots in the Design of Cognitive Therapies for People with Dementia Adriana Tapus* , Cristian Tapus , Maja Mataric University of Southern California [USA]	172
		FrBINT5.24	Long-Term Robot Therapy in a Health Service Facility for the Aged – a Case Study for 5 Years – Kazuyoshi Wada* , Takanori Shibata , Yukitaka Kawaguchi Tokyo Metropolitan University [Japan]	180
		FrBINT5.25	Investigation of Differences on Impressions of and Behaviors Toward Real and Virtual Robots between Elder People and University Students Tatsuya Nomura* , Miyuki Sasa Ryukoku University [Japan]	26
	Therapeutic Robotics5	FrBINT5.26	Safe Robot Therapy: Adaptation and Usability Test of a Three-Position Enabling Device for Use in Robot Mediated Physical Therapy of Stroke Andras Toth* , David Nyitrai , Mihaly Jurak , Istvan Merksz , Gabor Fazekas , Zoltán Dénes Budapest University of Technology and Economics [Hungary]	203
		FrBINT5.27	Setting of Training Load Using Theory of Functional Effective Muscle Yosuke Murakami* , Satoshi Komada , Junji Hirai Mie University [Japan]	46
		FrBINT5.28	A Performance Evaluation Method of a Passive Type Force Display and Rehabilitation System with Redundant Junji Furusho , Ying Jin* , Kunihiko Oda , Makoto Haraguchi , Takehito Kikuchi , Hiroki Akai Osaka University [Japan]	171
		FrBINT5.29	Remote Rehabilitation – the NeXOS Project: Lessons Learnt and Questions Raised David Bradley* , Camilo Acosta-Marquez , Mark Hawley , Simon Brownsell , Pam Enderby , Sue Mawson University of Abertay Dundee [United Kingdom]	12
		FrBINT5.30	A Virtual Environment-Based Paradigm for Improving Attention in TBI Assaf Dvorkin* , Felise Zollman , Kathleen Beck , Eric Larson , James Patton Rehabilitation Institute of Chicago [USA]	18
		FrBINT5.31	Virtual Reality Tasks to Enhance the Therapeutic Options of the Single Joint Rehabilitation Robot Imre Cikajlo* , Zlatko Matjačić Institute for Rehabilitation [Slovenia]	49
		FrBINT5.32	Virtually Offloading Body Mass for Rehabilitation: A Simulation Study Qi Lu , Ou Ma , Bing Qiao* Nanjing University of Aeronautics and Astronautics [China]	183